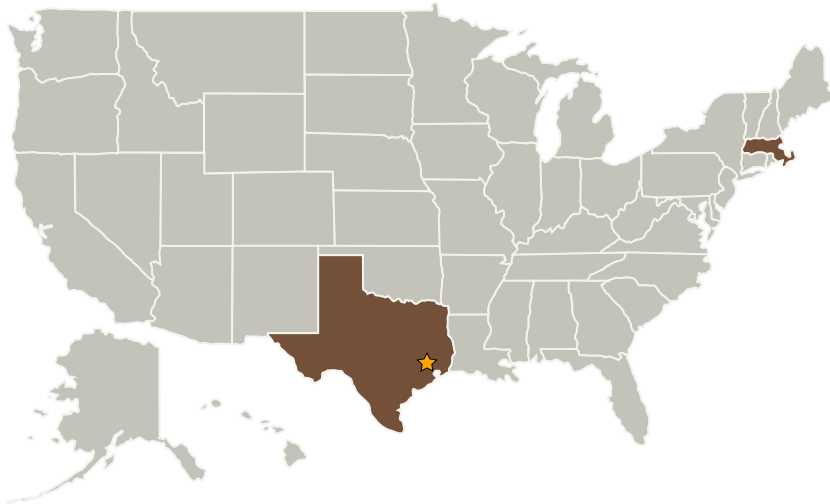


A Velocity-Control Framework for Kinematically Redundant Manipulators, Phase I

Completed Technology Project (2001 - 2002)



Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Type	Location
★ Johnson Space Center(JSC)	Lead Organization	NASA Center	Houston, Texas
Energid Technologies	Supporting Organization	Industry	Cambridge, Massachusetts

Primary U.S. Work Locations	
Massachusetts	Texas



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Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Center / Facility:

Johnson Space Center (JSC)

Responsible Program:

Small Business Innovation Research/Small Business Tech Transfer

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Completed Technology Project (2001 - 2002)



Project Management

Program Director:

Jason L Kessler

Program Manager:

Carlos Torrez

Principal Investigator:

Bradley R Williams

Technology Areas

Primary:

- TX06 Human Health, Life Support, and Habitation Systems
 - └ TX06.3 Human Health and Performance
 - └ TX06.3.5 Food Production, Processing, and Preservation